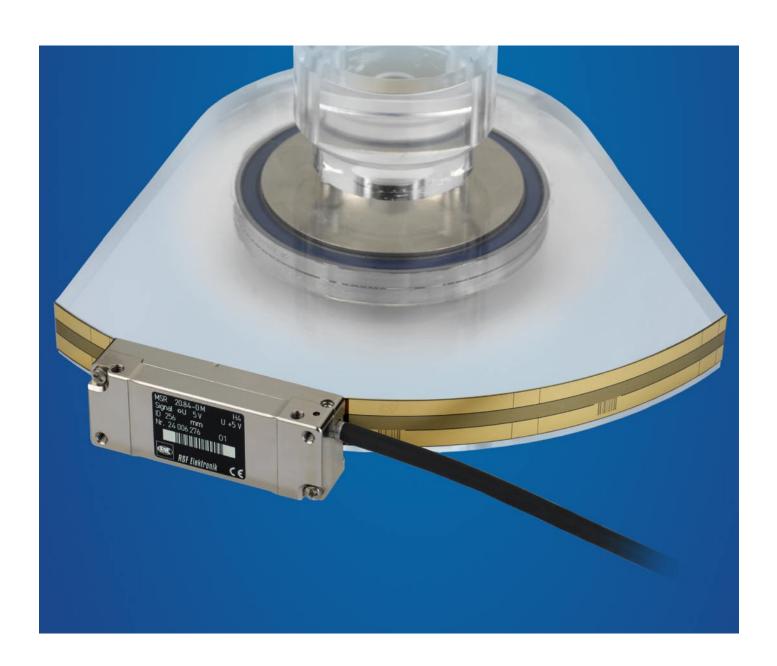


MSR 20

Modular Segment Rotary Encoder with singlefield scanning





MSR 20 Technical data

Scanning unit: 40 µm grating pitch

Scale model	Grating pitch	Integrated interpolation	Max. velocity	Max. output frequency resp. edge separation a _{min}
Sinusoidal voltage signals				
MSR 20.04	40 μm	-	10 m/s	250 kHz
Square wave signals via Line Driver with integrated Subdividing				
MSR 20.64	40 μm	times 5	6 m/s	300 ns
MSR 20.74	40 μm	times 10	3 m/s	300 ns
MSR 20.44	40 μm	times 20	2.2 m/s	200 ns
MSR 20.54	40 μm	times 25	1.8 m/s	200 ns
MSR 20.84	40 μm	times 50	1.8 m/s	100 ns
MSR 20.94	40 μm	times 100	0.9 m/s	100 ns

Scale tape - ring segment: version MSR 20.xx MKS

Scale unit: MKS = steel tape scale with adhesive tape

Accuracy of the grating pitch (stretched): ±15 µm/m

Mounting aid: optional accessories

Mounting control: electronic signal test/set-up boxes PG-x

Operating temperature range: 0°C to +50°C

(coefficient of expansion of the shaft between 9 x 10-6 K-1 and 12 x 10-6 K-1)

Temperature range of storage: -20°C to +70°C

Weight depending (approx.): 30 g (scanning unit without cable), 20 g/m (steel tape scale)

· Sinusoidal voltage signals MSR 20.00

Signal-outputs (optional):

Power supply:

+5V±5%, max. 130 mA (unloaded)

Output signals:

Encoder signals: 0.6 Vpp to 1.2 Vpp, typ. 1 Vpp with terminating resistor $Zo = 120 \Omega$ Reference pulse: 0.2 V to 0.85 V, typical 0.5 V (useable component) with terminating resistor Zo = 120Ω

- Square wave signals (single ended) with integrated Subdividing Electronics
- Square wave signals (differential) via Line Driver RS 422 Standard with integrated Subdividing Electronics

MSR 20.64 = times 5 MSR 20.74 = times 10

MSR 20.44 = times 20

MSR 20.54 = times 25

MSR 20.84 = times 50

MSR 20.94 = times 100

Power supply:

separated by n x 50 mm

+5 V ±5%, max. 165 mA (unloaded)

